

# IGDA Unity SIG II

AI in Unity

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# AI in Unity

- Sensors
- Decision logic
- Navigation

# Sensors

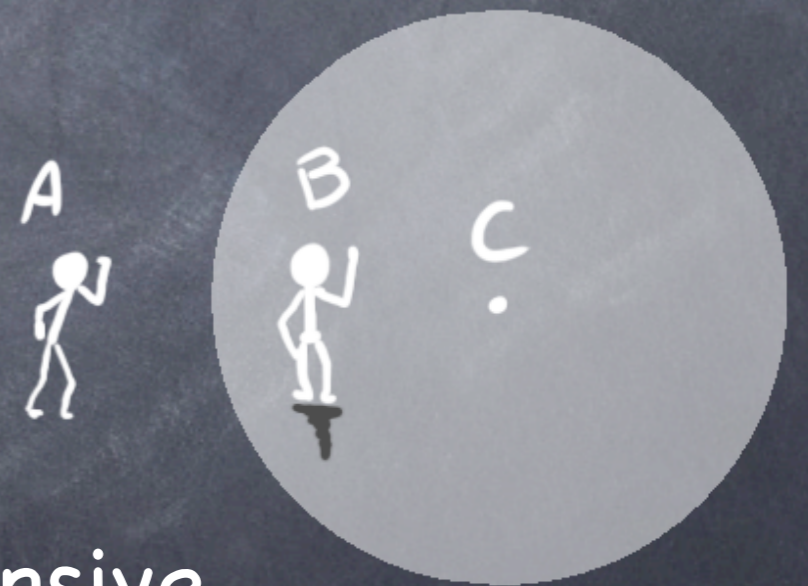
- Active
- "Passive"
- Message driven
- Second pass filtering
- Additional sensors or inclusion areas

# Active

- Using `Physics.OverlapSphere`
- Iterating list of target objects

# Using Physics.OverlapSphere

- Entities already represented in the physics simulation
- Filter by layer mask
- Cheap radius check
- Manual physics checks are expensive



# Manual physics checks are expensive

- Do not check each frame
- Regular physics run at a fixed framerate of 20 fps per default
- Adapt polling frequency to when the data is needed. Setting up the sensor as a service for the behaviour logic to use is a good best practice

# Iterating list of target objects

- Central registry
- Objects of interest register with a singleton `OnEnable` and unregister `OnDisable`
- Sensors filter through this list when needed
- Registry can do early sorting and grouping based on meta data
- `Object.GetObjectsOfType`

# "Passive"

- Using physics triggers
- The physics simulation is running anyway, being clever about polling and prediction
- Requires either extra manual setup of the transform tree or initialization work
- You are served the data whether you need it or not
- Use layer filtering via the layer mask table or `Physics.IgnoreCollision`
- Most likely need to forward collision information from a child GO to the central sensor logic
- Radar structure



# Message driven

- Central monitor
  - Polling and interpreting state changes on monitored subjects
  - Redirection of messages from clients
- Relative broadcast
  - Using active sensor to determine target audience
  - Transmitting messages to each member

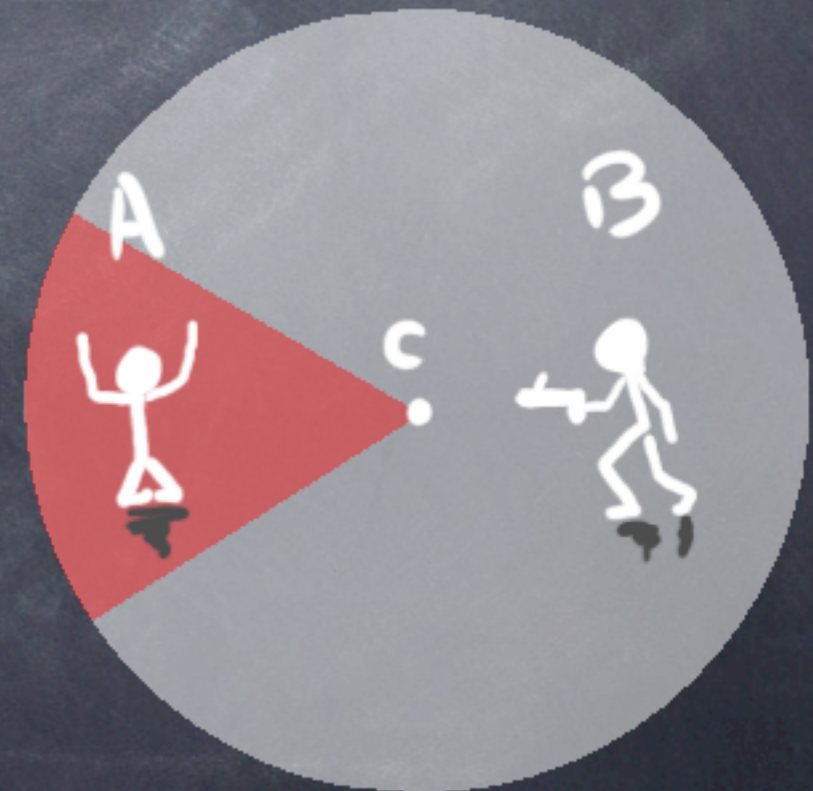
# Second-pass filtering

- Limit object list based on meta data
  - Tag filtering – more expensive than layer mask, but operating on already filtered data set
  - Component based sorting – GetComponent

# Second-pass filtering

- Visibility cone

```
Vector3.Angle (  
    transform.forward,  
    targetTransform.position - transform.position  
) < coneAngle * 0.5f
```



# Additional filters or inclusion areas

- Proximity overriding visibility cone
- "Audio" / event sensor
- Crowd influence - dispersal and relaxation

# Decision logic

- Whatever is wrong with a bunch of nested if-statements?
- Useful state machine setups
- Available middleware

# Whatever is wrong with a bunch of nested if-statements?

- It is just logic after all
- Systems handle abstraction and help keep you sane
- Does the term "spaghetti code" mean anything to you?

# Useful state machine setups

- FSM combines state tracking and handling
- Simple to understand system
- Very slim implementation

# Example:

enum + switch in AI update + function call



# Example:

enum + delegate + dictionary in abstract class

# Available middleware

- Why? Additional abstraction. Shortens the distance between idea and implementation
- PlayMaker [video]
- Behave [demo]

# Getting Started: PlayMaker Basics

Demo: Behave

# Navigation

- Setting up simple pathes
- Available middleware

# Setting up simple pathes

- Linking transforms via linked list of node components
- Keep track of next node
- Adjust force or direction vector to fit - slerp
- Basic steering

# Available middleware

- Aron Grandberg "A\* Pathfinding"
- Path
- UnitySteer